

# LED controller IC

## BCR450

Small Signal Discretes



Never stop thinking

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## **BCR450, LED controller IC**

**Revision History: 2007-09-26, Rev. 2.1**

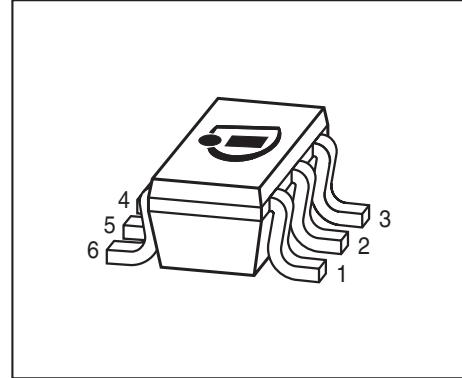
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**Previous Version: 2007-03-23, Rev. 1.0**

## 1 Bipolar Power LED Controller IC

### Features

- Bipolar power technology
- Voltage drop across sense resistor only 0.1...0.2 V
- Maximum operating voltage: 27 V
- Over voltage protection
- Temperature shut down mechanism
- Extremely precise bandgap voltage reference
- Low shut down current < 50 nA in operating voltage range
- Maximum operating output current: 85 mA
- Maximum LED current of 2.5 A possible by using external power transistors
- Digital On/Off switch
- PWM control for LED brightness possible
- Minimum external component required (sense resistor)
- Small package: 2.9 mm x 2.5 mm x 1.1 mm (TSOP6 / SC74)



### Applications

- LED controller for industrial applications, not qualified for automotive applications
- Universal constant current source
- General illumination e.g. retrofit
- Residential architectural and industrial commercial lighting for in- and outdoor
- Signal and marker lights for orientation or navigation (e.g. steps, exit ways, etc.)

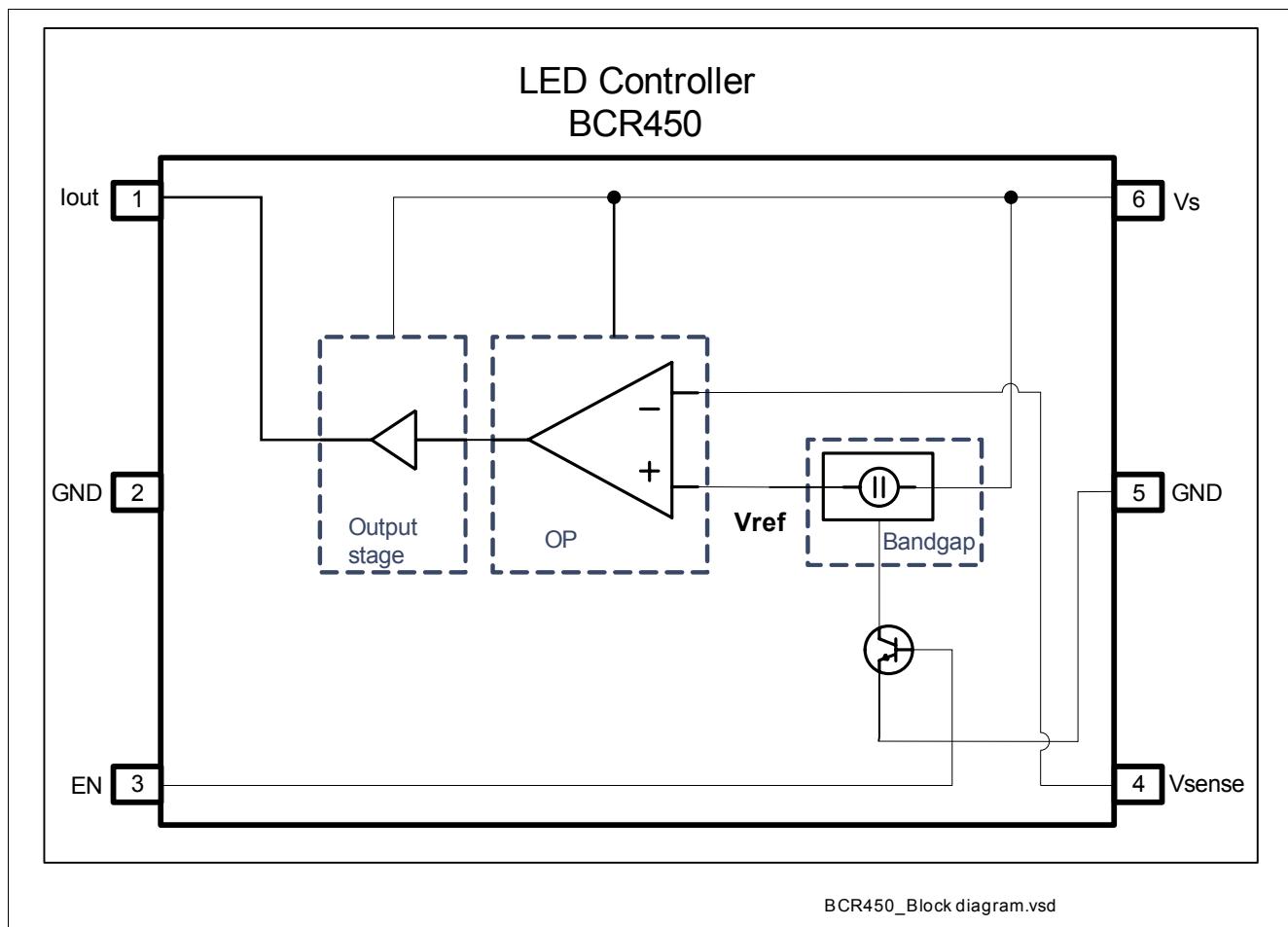
## 2 Description

The BCR450 is a low cost LED controller IC for industrial applications realized in a bipolar IC technology. The LED Controller is capable to drive high current, high brightness LEDs up to 2.5 A by using additional external output stages as "booster" transistors. For LED currents up to 85 mA the IC can be used as a stand alone device and requires only one voltage sense resistor as an external component

The current supply uses a sense control function with feedback mechanism that regulates the LED current.

The IC can be switched on and off by an external signal, which is also suitable to regulate brightness of the LEDs by PWM dimming. The precise internal bandgap stabilizes the circuit and provides stable current conditions over temperature range.

Furthermore, over voltage protection and temperature shut down mechanism enforce the IC to protect attached LEDs.

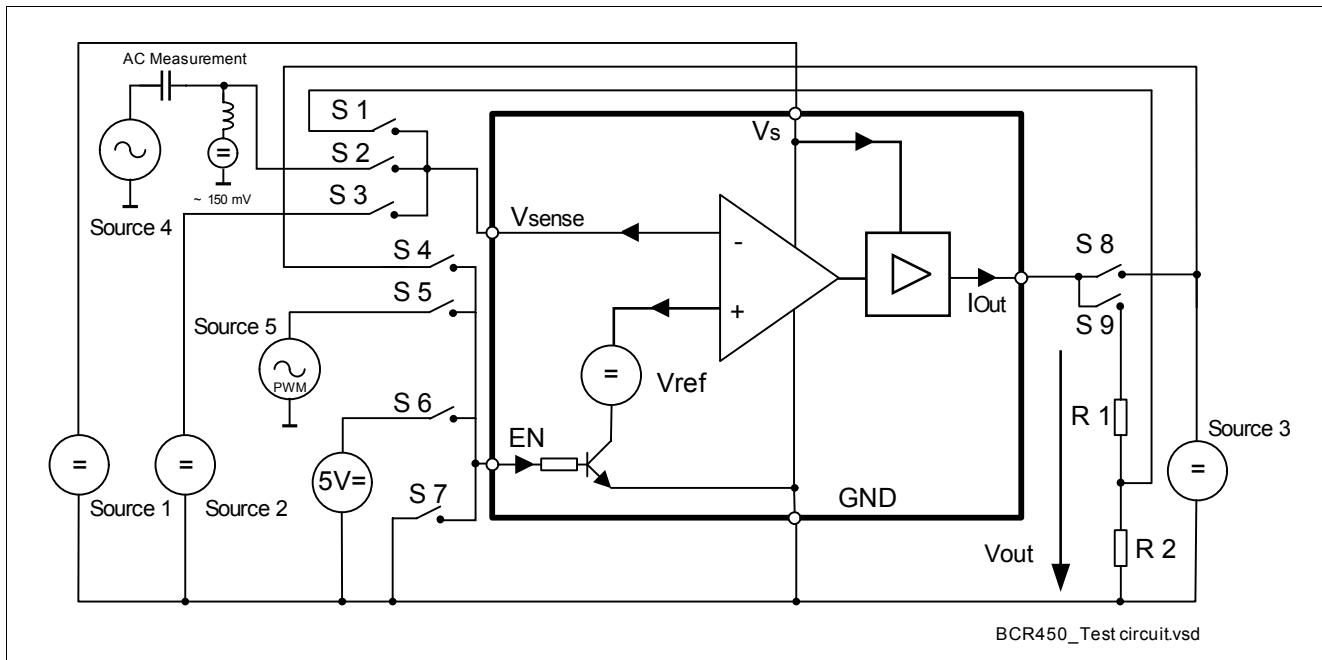


**Figure 1 Block diagram**

#### Pin Definition

**Table 1 Pin definition and function**

Pin number	Pin Symbol	Function
1	$I_{out}$	Controlled output current to drive LEDs
2	$GND$	IC ground
3	$EN$	Power On control voltage pin ( <i>PWM input</i> )
4	$V_{sense}$	Sense control voltage pin for internal feedback mechanism
5	$GND$	IC ground
6	$V_s$	Supply voltage



**Figure 2** Electrical test circuit

### Maximum Ratings

**Table 2** Maximum ratings

Parameter	Symbol	Limit Value	Unit
Supply voltage	$V_s$	40	V
Sense Voltage	$V_{sense}$	200	mV
Output current	$I_{out}$	100	mA
Total Power Dissipation; $T_s = 112.5^\circ\text{C}$	$P_{tot}$	500	mW
Junction temperature	$T_J$	150	°C
Storage temperature range	$T_{STG}$	-65... 150	°C
ESD capability Human Body Model <sup>1)</sup>	$V_{ESD\_HBM}$	4000	V
ESD capability Machine Model <sup>2)</sup>	$V_{ESD\_MM}$	400	V

1) For ESD testing, the chip was mounted in a TSOP-6 package on an application board, where GND is electrically connected to the chip GND

2) For ESD testing, the chip was mounted in a TSOP-6 package, where GND is electrically connected to the chip GND

### Thermal resistance

**Table 3** Thermal resistance

Parameter	Symbol	Value	Unit
Junction - solder point	$R_{thJS}$	75	K/W

### 3 Electrical Characteristics

#### 3.1 DC Characteristics

$8 \text{ V} < V_s < 27 \text{ V}$ ;  $-30^\circ\text{C} < T_j < 150^\circ\text{C}$ , all voltages with respect to ground; current directions as given in [Figure 2](#); unless otherwise specified

All parameters are tested at  $25^\circ\text{C}$ , unless otherwise specified

**Table 4 DC Characteristics**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Overall current consumption	$I_s$ <sub>short</sub>	70	90		mA	$I_s$ short; $V_s = 8 \text{ V}$ $V_{sense} = 20 \text{ mV}$
Overall current consumption	$I_s$ <sub>short</sub>	70	90		mA	$I_s$ short; $V_s = 27 \text{ V}$ $V_{sense} = 20 \text{ mV}$
Overall current consumption	$I_s$ <sub>short</sub>			600	$\mu\text{A}$	$I_s$ short; $V_s = 42 \text{ V}$ $V_{sense} = 20 \text{ mV}$
Overall current consumption open load	$I_s$ <sub>open load</sub>	200	250	500	$\mu\text{A}$	$I_s$ open load; $V_s = 8 \text{ V}$ $V_{sense} = 200 \text{ mV}$
Overall current consumption open load	$I_s$ <sub>open load</sub>	250	350	600	$\mu\text{A}$	$I_s$ open load; $V_s = 27 \text{ V}$ $V_{sense} = 200 \text{ mV}$
Overall current consumption open load	$I_s$ <sub>open load</sub>	400	450	1000	$\mu\text{A}$	$I_s$ open load; $V_s = 42 \text{ V}$ $V_{sense} = 200 \text{ mV}$
Overall standby current consumption	$I_s$ <sub>standby</sub>			200	nA	$EN = 0 \text{ V}; V_s = 8 \text{ V}$ $V_{sense} = 20 \text{ mV}$
Overall standby current consumption	$I_s$ <sub>standby</sub>			200	nA	$EN = 0 \text{ V}; V_s = 27 \text{ V}$ $V_{sense} = 20 \text{ mV}$
Current of enable input	$I_{EN}$	20	40	70	$\mu\text{A}$	$V_{sense} = 0-200 \text{ mV}$
Current of driver output	$I_{outhigh}$	70	90		mA	$V_{sense} = 20 \text{ mV};$ $V_s = 8 \text{ V}$
Current of driver output	$I_{outlow}$			100	nA	$V_{sense} = 200 \text{ mV};$ $V_s = 8 \text{ V}$
Current of Sense input	$I_{sense}$			200	nA	$V_{sense} = 20 \text{ mV}$
Current of Sense input	$I_{sense}$			100	nA	$V_{sense} = 200 \text{ mV}$
Voltage of Driver output	$V_{out}$		6		V	$I_{out} = 15 \text{ mA};$ $S1, S6, S8, S9 = \text{on};$ $R1 = 390 \Omega;$ $R2 = 10 \Omega;$ see <a href="#">Figure 2</a>
Voltage of Sense input	$V_{sense}$	135	150	165	mV	$I_{out} = 15 \text{ mA}; V_s = 8 \text{ V}$ $S3, S6, S8 = \text{on};$ $R1 = 390 \Omega; R2 = 10 \Omega$ see <a href="#">Figure 2</a>

## Electrical Characteristics

**Table 4 DC Characteristics (cont'd)**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Voltage of Sense input	$V_{\text{sense}}$	135	150	165	mV	$I_{\text{out}} = 15 \text{ mA}$ ; $V_s = 27 \text{ V}$ S3, S6, S8 = on; $R1 = 390 \Omega$ ; $R2 = 10 \Omega$ see <a href="#">Figure 2</a>
Over voltage Protection	$V_{s, \text{OV}}$	27			V	$I_{\text{out}} > 0 \text{ A}$
Off- load output current	$I_{\text{CC2}}$	70			mA	$V_{\text{sense}} = 0 \text{ V}$
Delta sense voltage	$\Delta V_{\text{sense}}$	2	10	50	mV	$I_{\text{out}}$ : $0 \rightarrow 50 \text{ mA}$
Lowest sufficient battery voltage overhead	$V_s - V_{\text{out}}$		1.2		V	$I_{\text{out}} < 50 \text{ mA}$
Temperature shut down	$T_{\text{h}_{\text{TSD}}}$	150	170	190	°C	$I_{\text{out}} > 0 \text{ A}$ ; refer to $T_A$

### 3.2 AC Characteristics

$8 \text{ V} < V_s < 27 \text{ V}$ ;  $-30^\circ\text{C} < T_J < 150^\circ\text{C}$ , all voltages with respect to ground; current directions as given in [Figure 2](#); unless otherwise specified

All parameters are tested at  $25^\circ\text{C}$ , unless otherwise specified

**Table 5 AC Characteristics <sup>1)</sup>**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Open Loop Gain	$A_{\text{VD}}$		65		dB	$V_s = 8 \text{ V}$
	$A_{\text{VD}}$		70		dB	$V_s = 27 \text{ V}$
Unity Gain Bandwidth	$G_{\text{BW}}$		600		kHz	$V_s = 8 \text{ V}$
	$G_{\text{BW}}$		1000		kHz	$V_s = 27 \text{ V}$
Phase Margin <sup>2)</sup>	$PM_G$		109		°	$V_s = 8 \text{ V}$
	$PM_G$		102		°	$V_s = 27 \text{ V}$

1)  $V_{\text{out}} = 6 \text{ V}$ ; S2, S6, S8, S9 = on;  $R1 = 390 \Omega$ ;  $R2 = 10 \Omega$ , see [Figure 3](#)

2) Refer to Loop Gain

## Electrical Characteristics

### 3.3 Digital Signals

All parameters are tested at 25 °C, unless otherwise specified

**Table 6 Digital Control Parameter (EN)**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Power on control voltage range	$U_{\text{Pon}}$	-0.3		5	V	
Control voltage for power on	$U_{\text{On}}$	0.6	0.85	5	V	
Control voltage for power off	$U_{\text{Off}}$	-0.3		0.35	V	
PWM signal frequency	$f_{\text{PWM}}$			1000	Hz	$t_{\text{dutycycle}} = 1\%$ ; signal level reaches 100% in on and off mode
PWM Duty cycle	$t_{\text{dutyPWM}}$	5			%	$f = 5 \text{ KHz}$ ; signal level reaches 100% in on and off mode
PWM voltage	$U_{\text{PWM}}$			5	V	

### 3.4 Transient Parameters

$8 \text{ V} < V_S < 27 \text{ V}$ ;  $-30^\circ\text{C} < T_J < 150^\circ\text{C}$ , all voltages with respect to ground; current directions as given in [Figure 2](#); unless otherwise specified

All parameters are tested at 25 °C, unless otherwise specified

**Table 7 Digital Control Parameter (EN)**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Response Time	$T_{\text{ON}}$			10	μs	EN: 0 → 5 V @ $t_{\text{rise}} < 20 \text{ ns}$ $t_{\text{risetime}} @ (10\ldots90\%) * V_{\text{sense}}$ ( $I_{\text{out}} \sim 15 \text{ mA}$ ); $R_{\text{sense}} = 10 \Omega$ see <a href="#">Figure 4</a>
	$T_{\text{OFF}}$			70	μs	EN: 5 V → 0 @ $t_{\text{fall}} < 20 \text{ ns}$ $t_{\text{falltime}} @ (90\ldots10\%) * V_{\text{sense}}$ ( $I_{\text{out}} \sim 15 \text{ mA}$ ); $R_{\text{sense}} = 10 \Omega$ see <a href="#">Figure 4</a>

### 3.5 AC Test Circuits

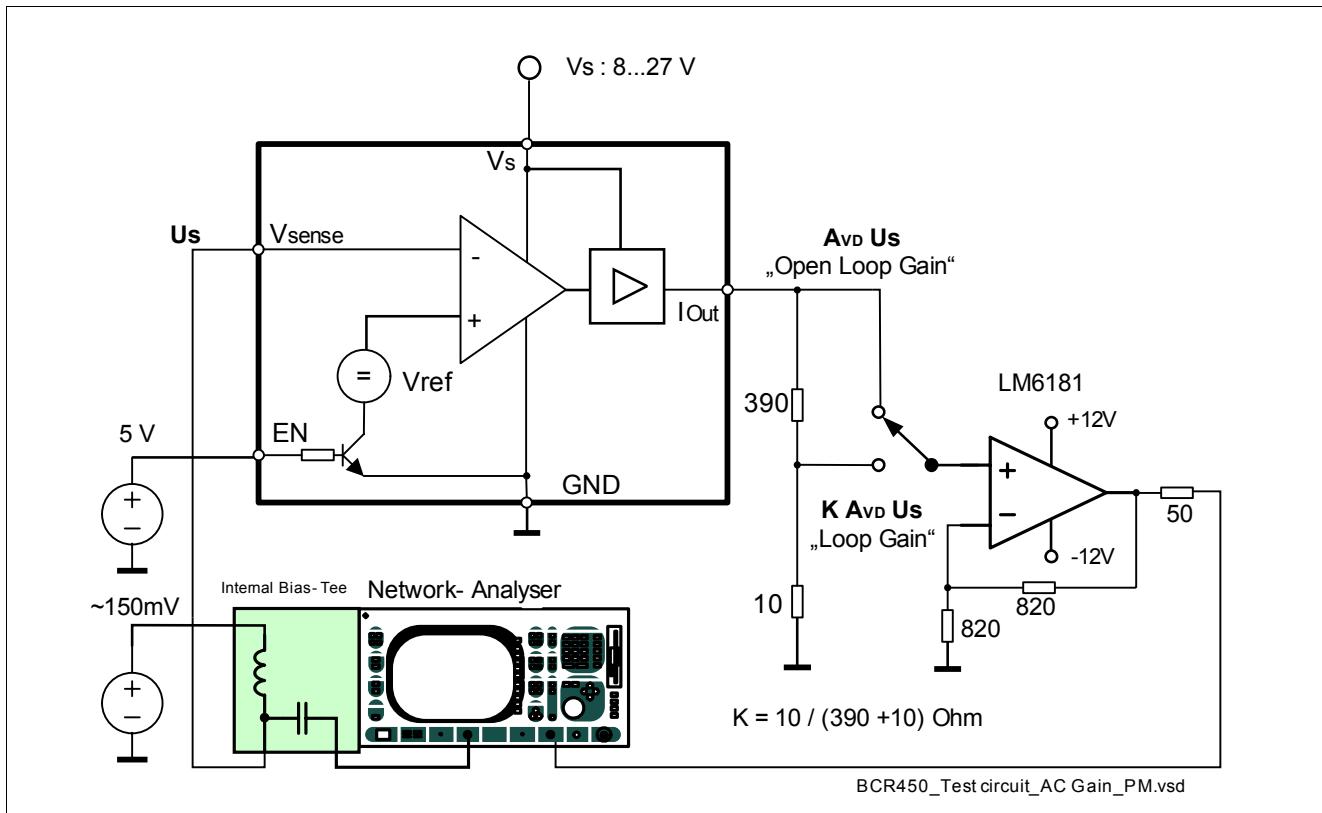


Figure 3 Electrical test circuit for open loop gain, loop gain and phase margin

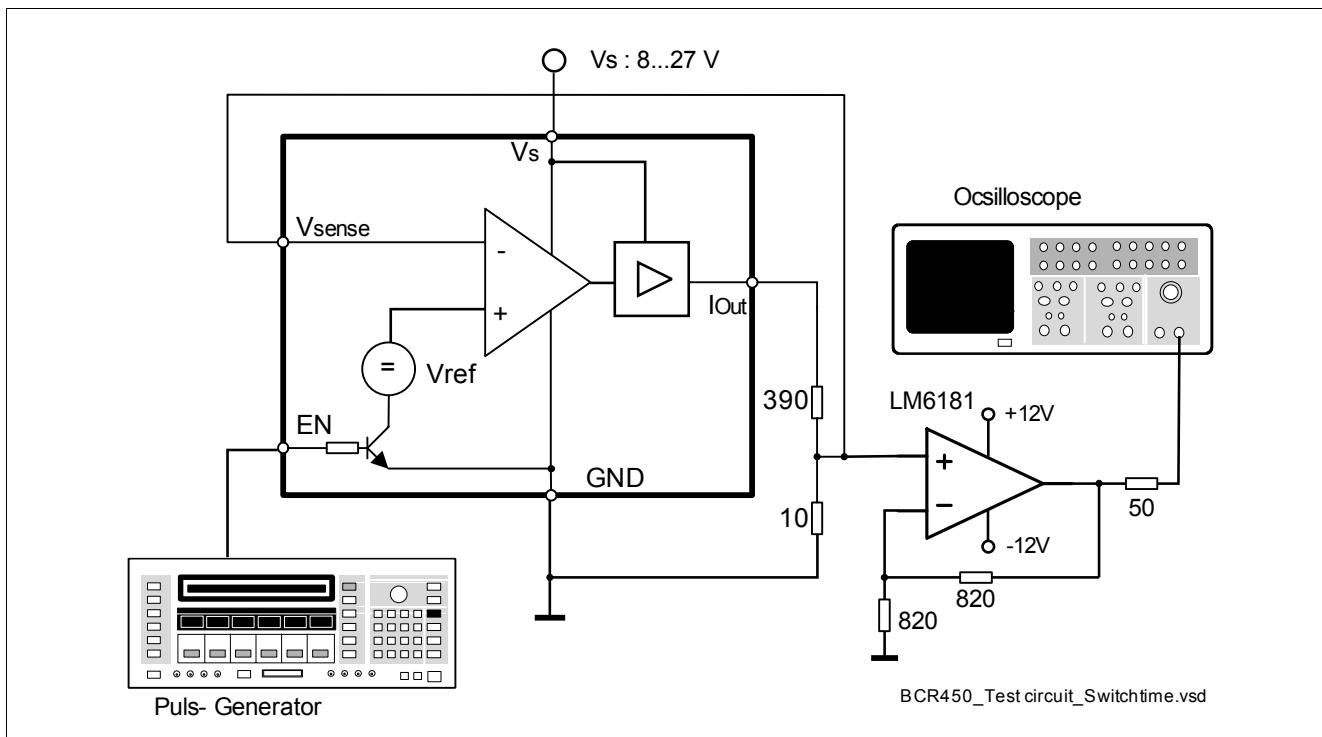


Figure 4 Electrical test circuit for response time

## 4 Measured Parameters

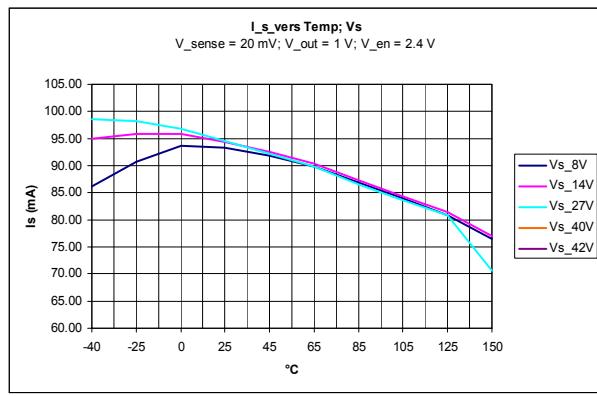
**BCR450 IC has been measured in test bench with undefined high thermal resistance**

This is valid for all diagrammed DC- and AC- Parameters

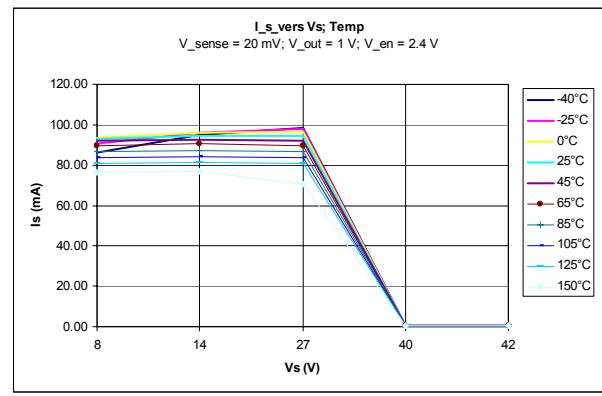
### 4.1 DC- Parameter

$$V_{\text{out}} = 1.0 \text{ V}, EN = 2.4 \text{ V}$$

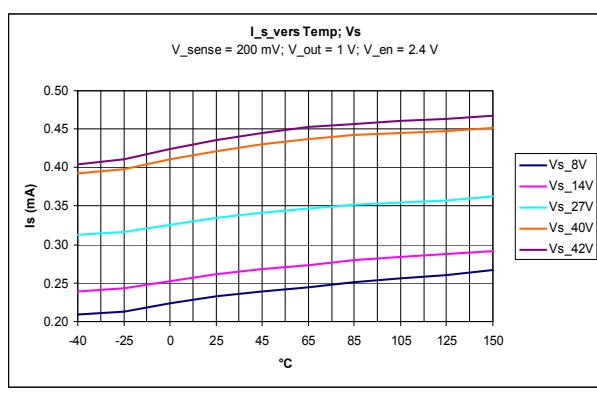
$I_S$  vers Temperature ( $V_S$ );  $V_{\text{sense}} = 20 \text{ mV}$



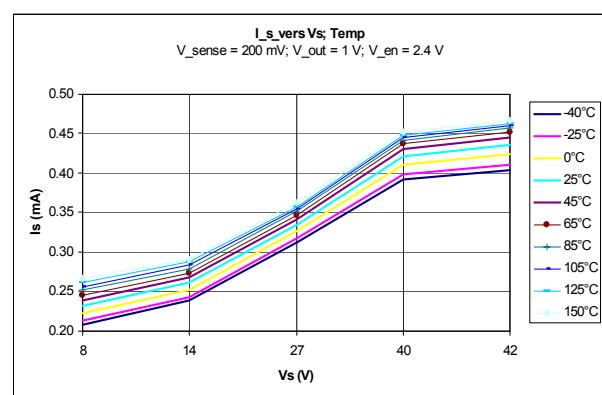
$I_S$  vers  $V_s$  (Temperature);  $V_{\text{sense}} = 20 \text{ mV}$

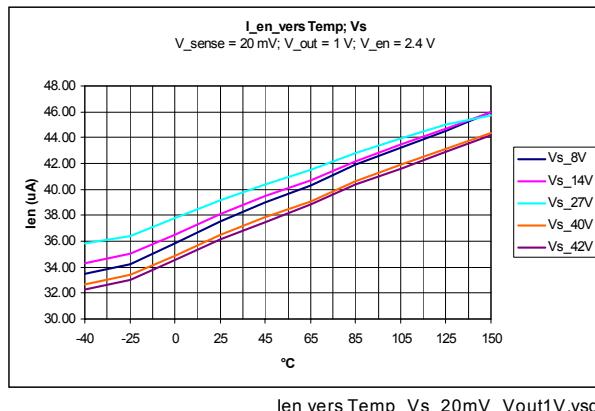
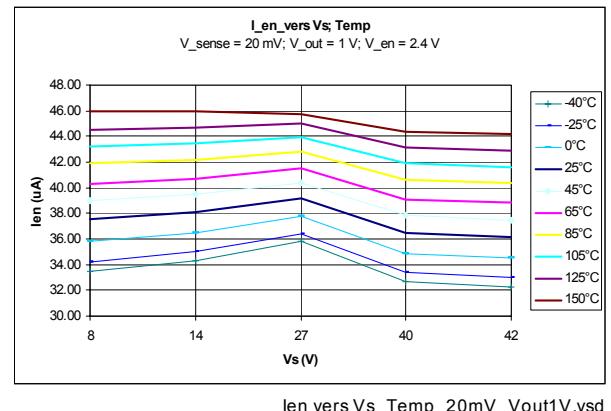
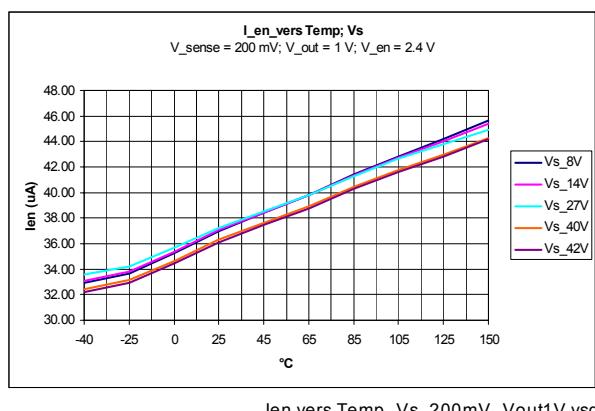
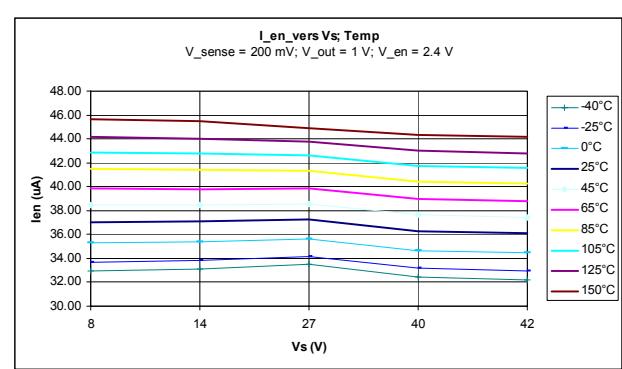
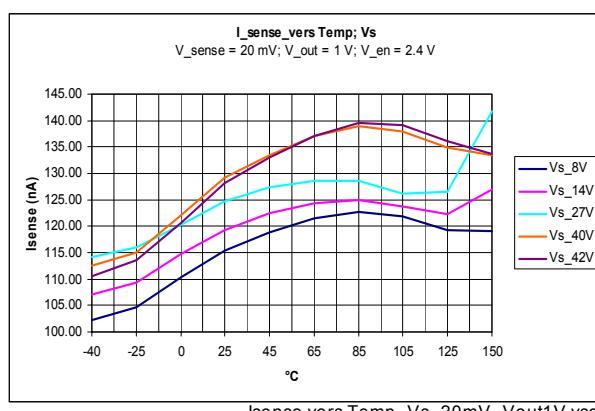
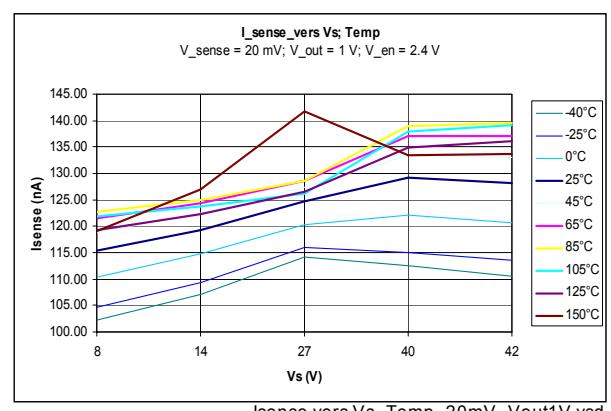


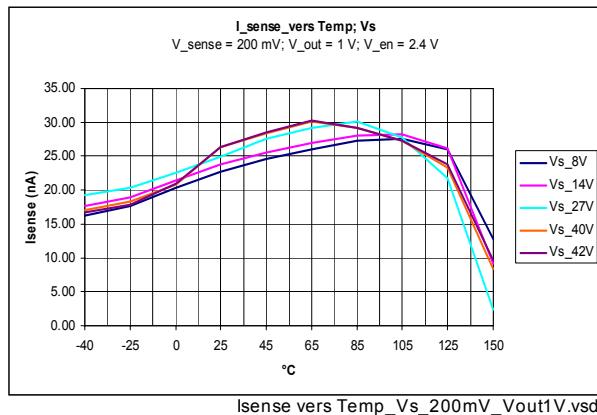
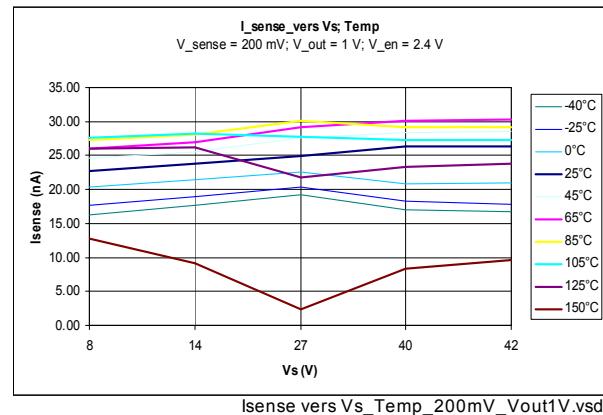
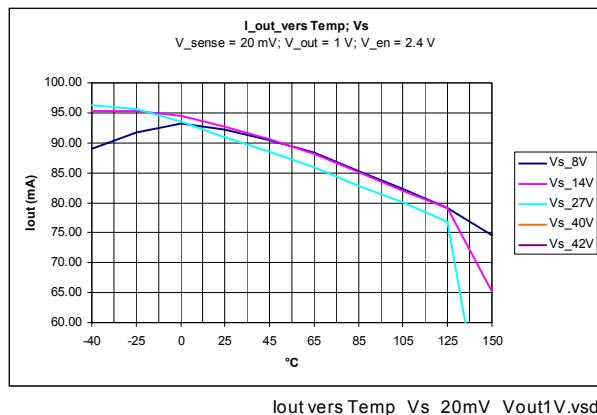
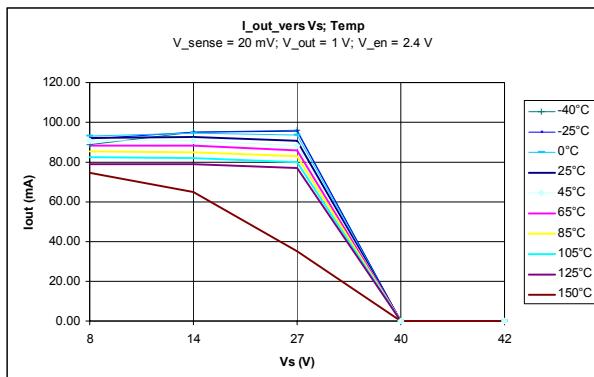
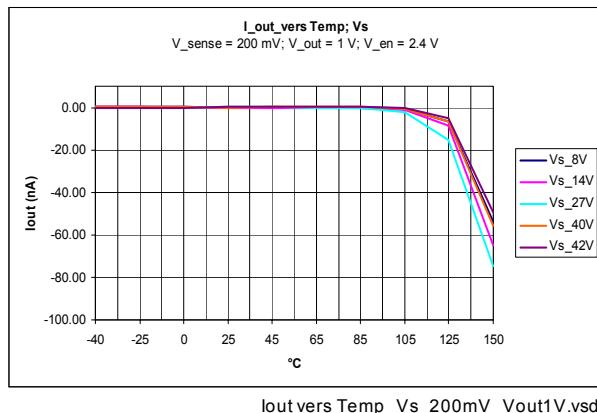
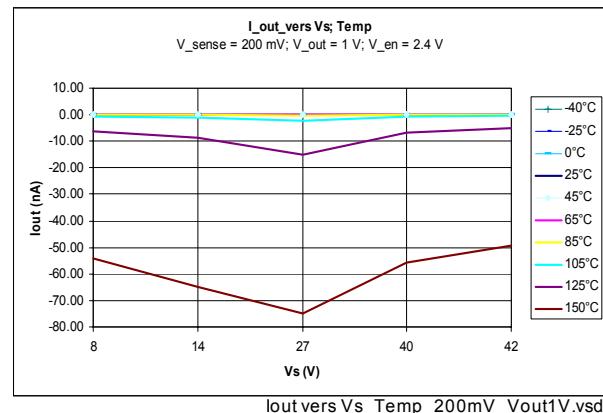
$I_S$  vers Temperature ( $V_S$ );  $V_{\text{sense}} = 200 \text{ mV}$



$I_S$  vers  $V_s$  (Temperature);  $V_{\text{sense}} = 200 \text{ mV}$



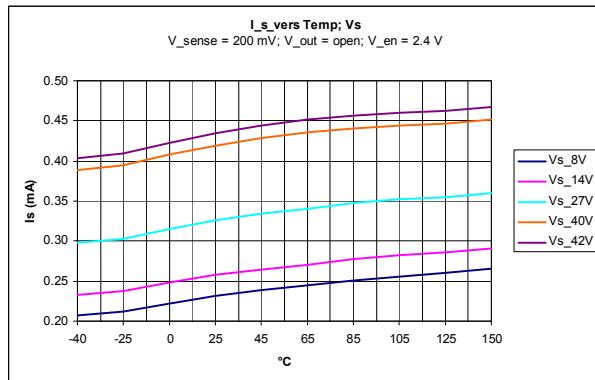
**Measured Parameters**
*I<sub>en</sub>* vers Temperature (*V<sub>S</sub>*); *V<sub>sense</sub>* = 20 mV

*I<sub>en</sub>* vers *V<sub>s</sub>* (Temperature); *V<sub>sense</sub>* = 20 mV

*I<sub>en</sub>* vers Temperature (*V<sub>S</sub>*); *V<sub>sense</sub>* = 200 mV

*I<sub>en</sub>* vers *V<sub>s</sub>* (Temperature); *V<sub>sense</sub>* = 200 mV

*I<sub>sense</sub>* vers Temperature (*V<sub>S</sub>*); *V<sub>sense</sub>* = 20 mV

*I<sub>sense</sub>* vers *V<sub>s</sub>* (Temperature); *V<sub>sense</sub>* = 20 mV


**Measured Parameters**
 $I_{\text{sense}}$  vers Temperature ( $V_S$ );  $V_{\text{sense}} = 200 \text{ mV}$ 

 $I_{\text{sense}}$  vers  $V_S$  (Temperature);  $V_{\text{sense}} = 200 \text{ mV}$ 

 $I_{\text{out}}$  vers Temperature ( $V_S$ );  $V_{\text{sense}} = 20 \text{ mV}$ 

 $I_{\text{out}}$  vers  $V_S$  (Temperature);  $V_{\text{sense}} = 20 \text{ mV}$ 

 $I_{\text{out}}$  vers Temperature ( $V_S$ );  $V_{\text{sense}} = 200 \text{ mV}$ 

 $I_{\text{out}}$  vers  $V_S$  (Temperature);  $V_{\text{sense}} = 200 \text{ mV}$ 


**Measured Parameters**

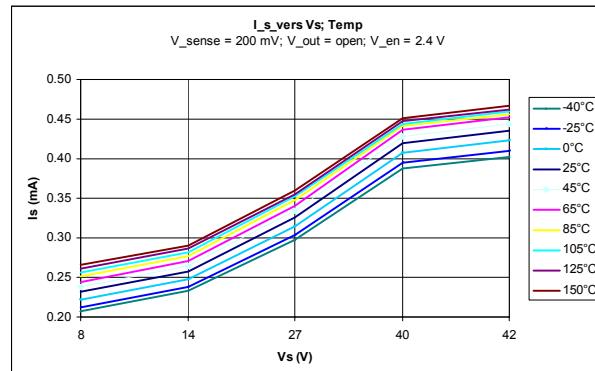
$V_{out} = \text{open}$ ,  $V_{sense} = 200 \text{ mV}$ ;  $EN = 2.4 \text{ V}$

$I_s$  vers Temperature ( $V_S$ )



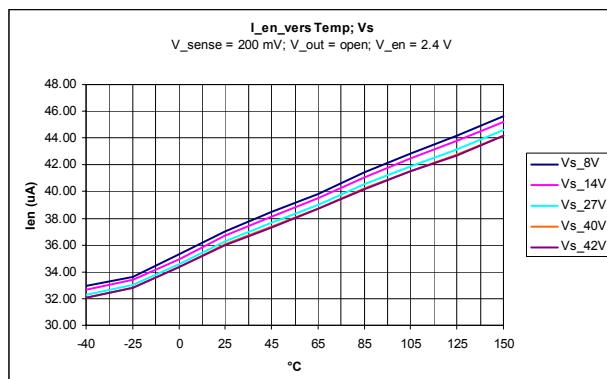
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$I_s$  vers  $V_s$  (Temperature)



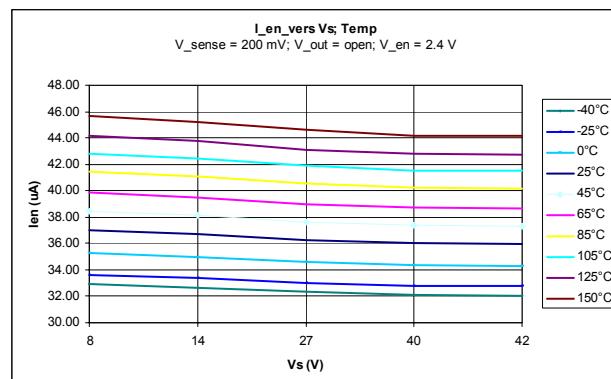
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$I_{en}$  vers Temperature ( $V_S$ )



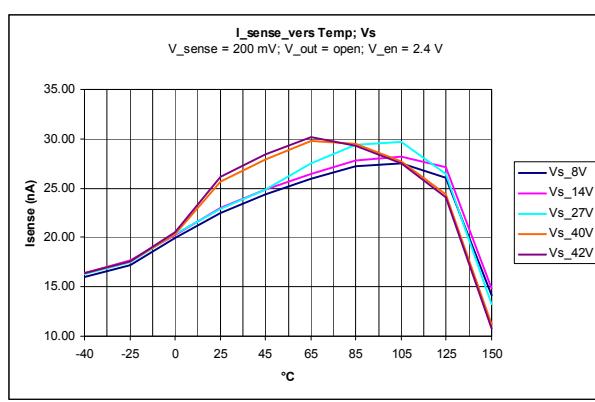
I\_en vers Temp\_Vs\_200mV\_Voutopen.vsd

$I_{en}$  vers  $V_S$  (Temperature)



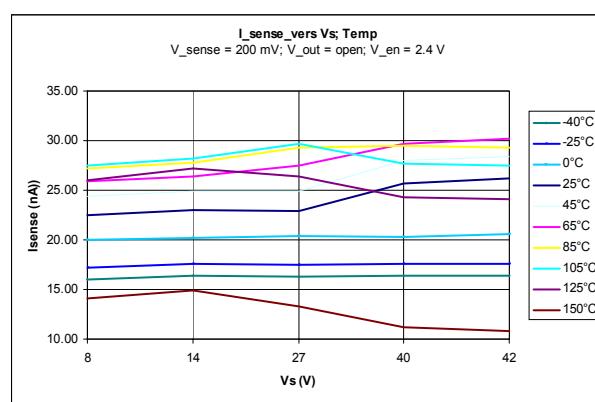
I\_en vers Vs\_Temp\_200mV\_Voutopen.vsd

$I_{sense}$  vers Temperature ( $V_S$ )



Isense vers Temp\_Vs\_200mV\_Voutopen.vsd

$I_{sense}$  vers  $V_S$  (Temperature)

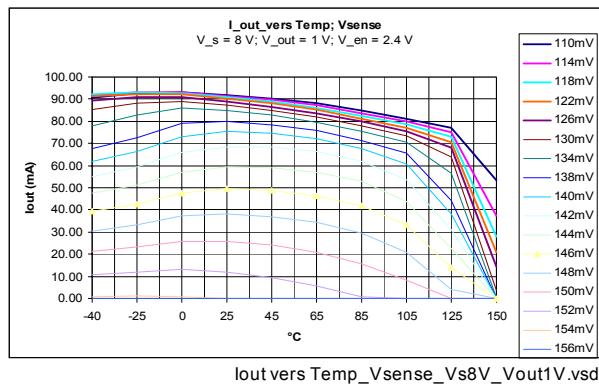


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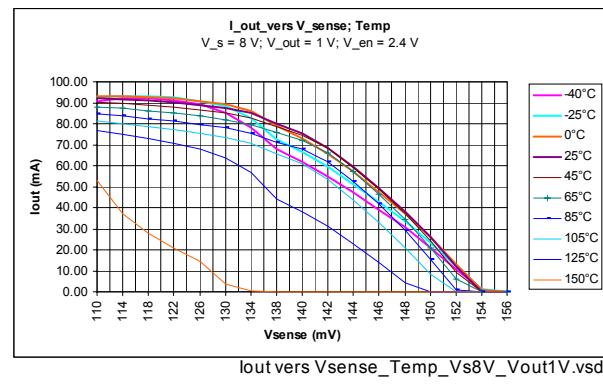
**Measured Parameters**

$V_s = 8 \text{ V}$ ,  $V_{\text{out}} = 1 \text{ V}$ ; EN = 2.4 V

$I_{\text{out}}$  vers Temperature ( $V_{\text{Sense}}$ )

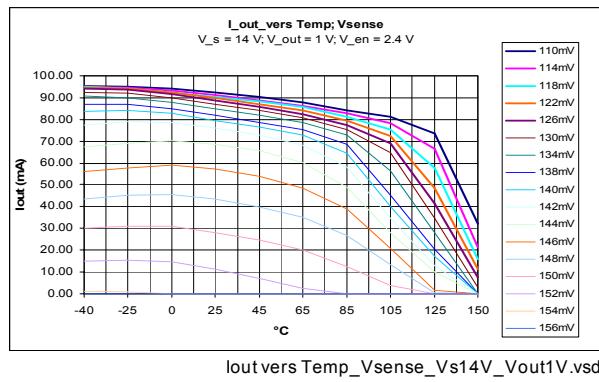


$I_{\text{out}}$  vers  $V_{\text{sense}}$  (Temperature)

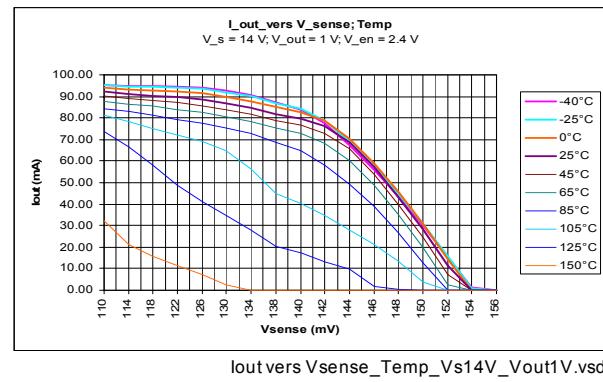


$V_s = 14 \text{ V}$ ,  $V_{\text{out}} = 1 \text{ V}$ ; EN = 2.4 V

$I_{\text{out}}$  vers Temperature ( $V_{\text{Sense}}$ )

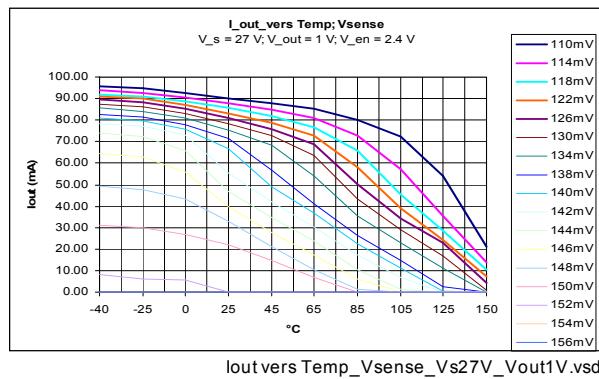


$I_{\text{out}}$  vers  $V_{\text{sense}}$  (Temperature)

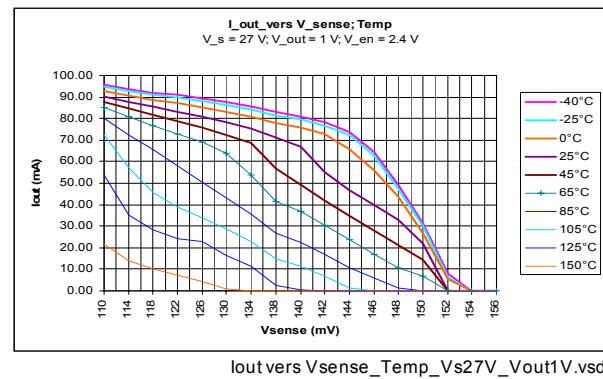


$V_s = 27 \text{ V}$ ,  $V_{\text{out}} = 1 \text{ V}$ ; EN = 2.4 V

$I_{\text{out}}$  vers Temperature ( $V_{\text{Sense}}$ )



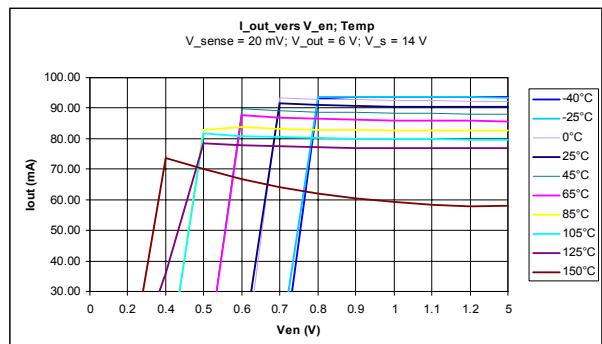
$I_{\text{out}}$  vers  $V_{\text{sense}}$  (Temperature)



**Measured Parameters**

$V_s = 14 \text{ V}$ ,  $V_{\text{out}} = 6 \text{ V}$ ; EN = 20 mV

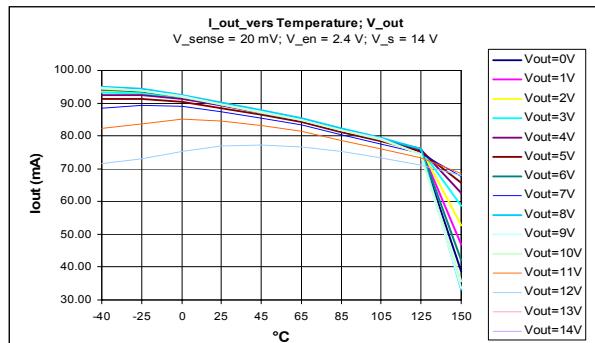
$I_{\text{out}}$  vers EN (*Temperature*)



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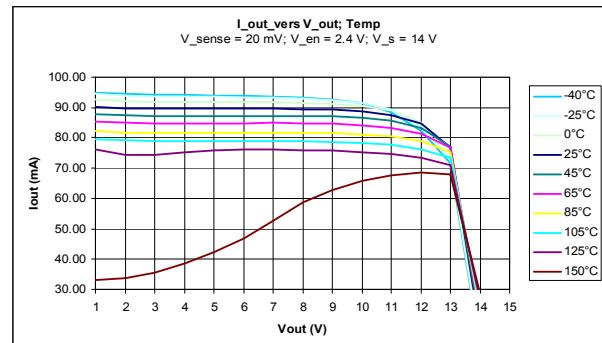
$V_s = 14 \text{ V}$ ,  $V_{\text{sense}} = 20 \text{ mV}$ ; EN = 2.4 V

$I_{\text{out}}$  vers Temperature ( $V_{\text{out}}$ )



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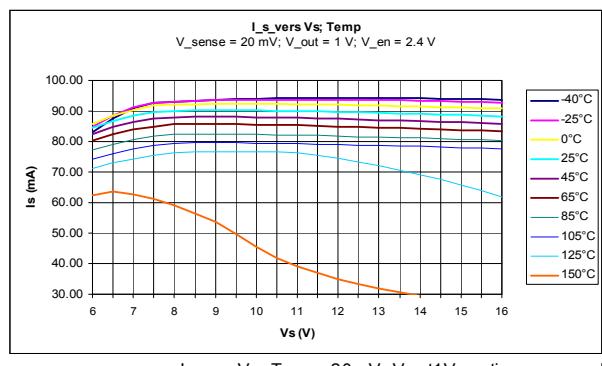
$I_{\text{out}}$  vers  $V_{\text{out}}$  (*Temperature*)



Iout vers Vout\_Vsense20mV\_Vs14V.vsd

$V_{\text{out}} = 1 \text{ V}$ ,  $V_{\text{sense}} = 20 \text{ mV}$ ; EN = 2.4 V

$I_s$  vers  $V_s$  (*Temperature*)

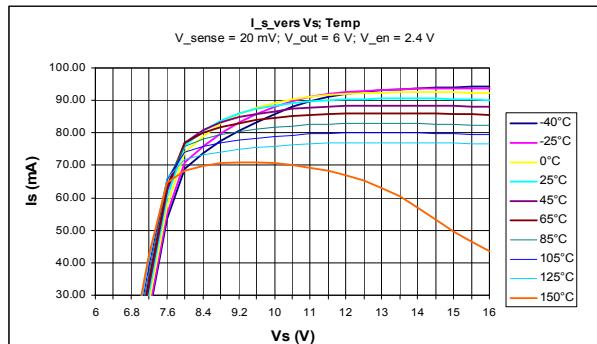


Is vers Vs\_Temp\_20mV\_Vout1V\_entire range.vsd

**Measured Parameters**

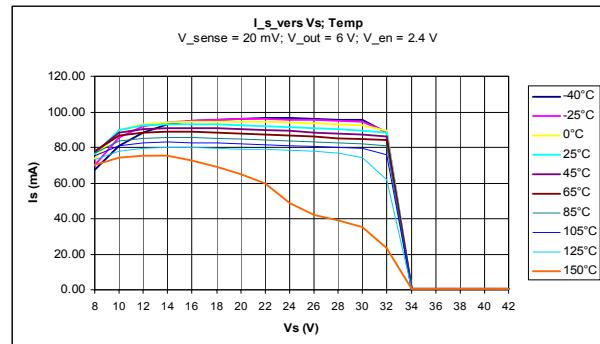
**$V_{out} = 6 \text{ V}$ ,  $V_{sense} = 20 \text{ mV}$ ; EN = 2.4 V**

$I_s$  vers  $V_S$  (Temperature)



Is vers Vs\_Temp\_20mV\_Vout6V.vsd

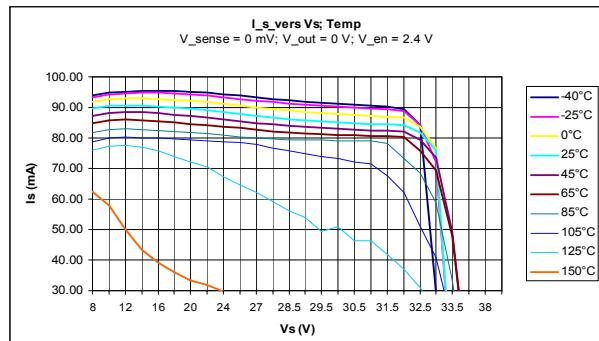
$I_s$  vers  $V_S$  (Temperature)



Is vers Vs\_Temp\_20mV\_Vout6V\_entire range.vsd

**$I_s$  short  $\rightarrow V_{out} = 0 \text{ V}$ ,  $V_{sense} = 0 \text{ mV}$ ; EN = 2.4 V**

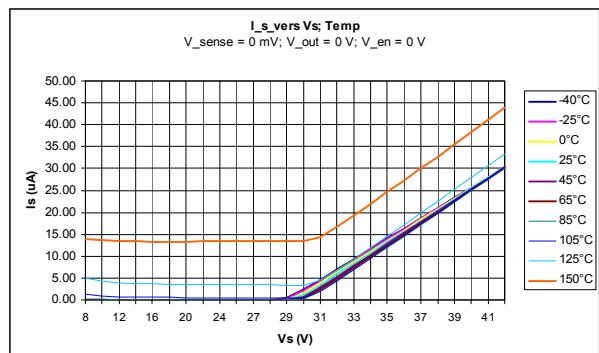
$I_s$  vers  $V_S$  (Temperature)



Is vers Vs\_Temp\_0mV\_Vout0V.vsd

**$I_s$  standby  $\rightarrow V_{out} = 0 \text{ V}$ ,  $V_{sense} = 0 \text{ mV}$ ; EN = 0 V**

$I_s$  vers  $V_S$  (Temperature)

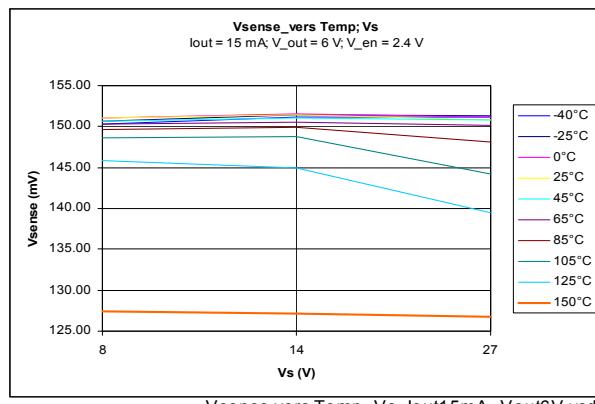


Is vers Vs\_Temp\_0mV\_Vout0V\_EN0V.vsd

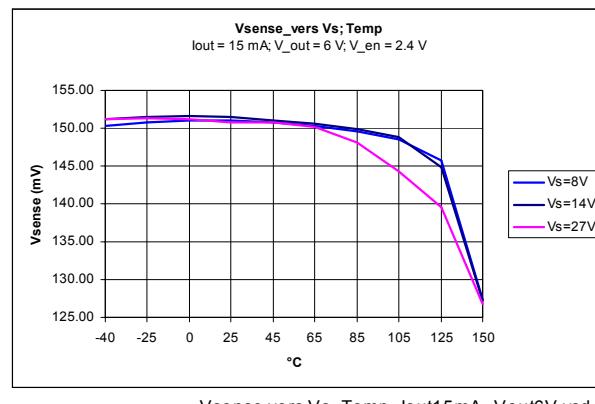
## Measured Parameters

$V_{out} = 6 \text{ V}$ ,  $I_{out} = 15 \text{ mA}$ ; EN = 2.4 V

$V_{sense}$  vers Temperature ( $V_s$ )



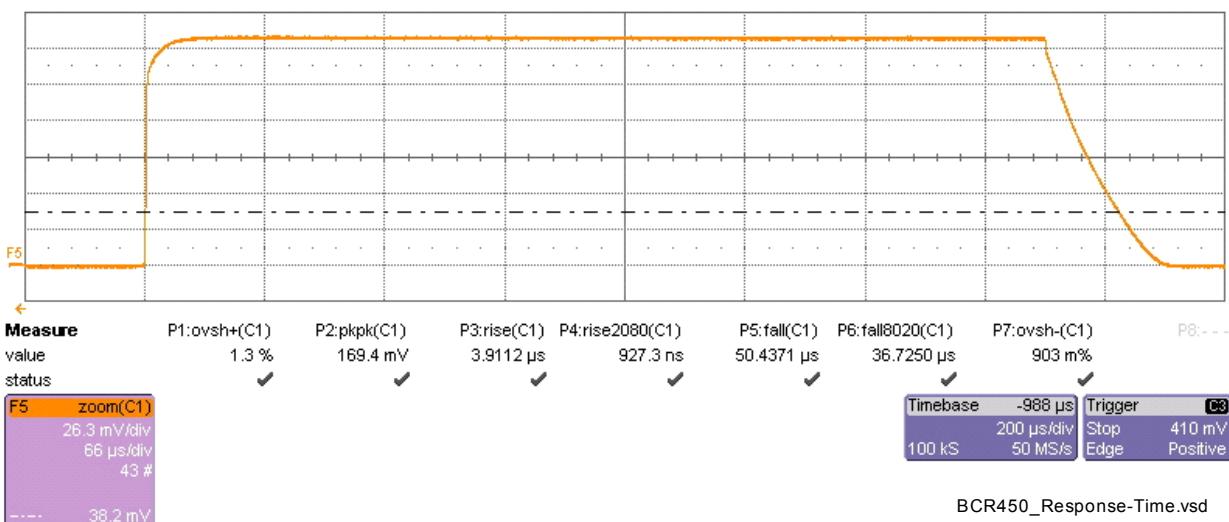
$V_{sense}$  vers  $V_S$  (Temperature)

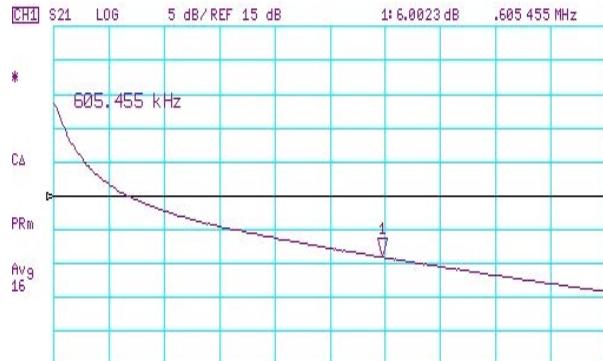
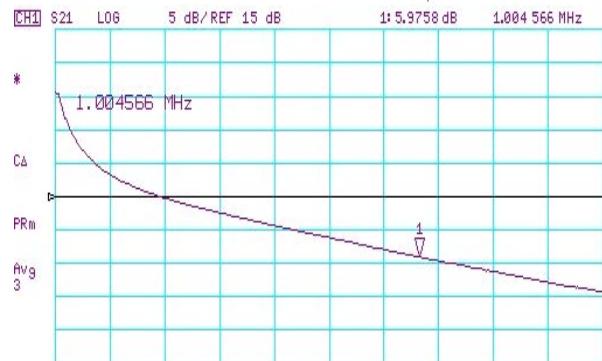


## 4.2 AC- Parameter

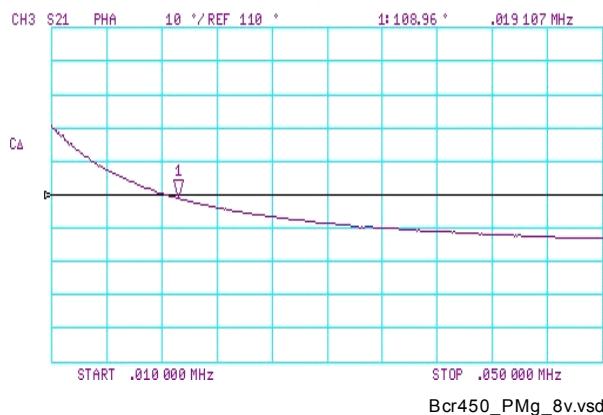
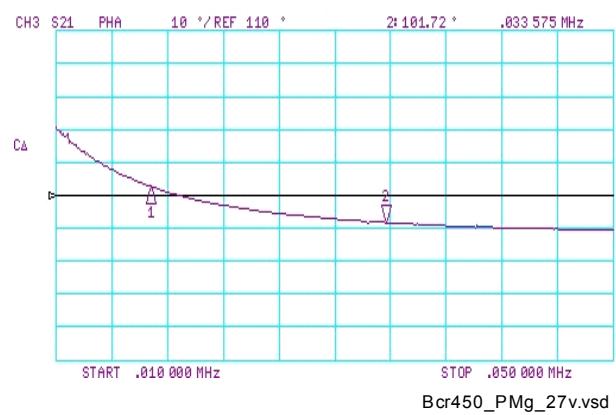
Response Time

$T_{on}$  &  $T_{off}$ ;  $V_s = 12 \text{ V}$ ;  $f_{Pulse} = 1 \text{ KHz}$ ;  $t_{duty} = 50\%$



**Measured Parameters**
**Unity Gain Bandwidth  $G_{BW}$ ;  $V_s = 8 \text{ V}^1$** 

**Unity Gain Bandwidth  $G_{BW}$ ;  $V_s = 27 \text{ V}$** 


- 1) Marker read out at 6 dB due to the highohmic load of the operational amplifier, NWA is calibrated with 50 Ohm

**Phase Margin  $PM_G$ ;  $V_s = 8 \text{ V}$** 

**Phase Margin  $PM_G$ ;  $V_s = 27 \text{ V}$** 


## 5 Evaluation Board

The evaluation board is designed to test the BCR450 as a stand alone device for lower LED current applications and also with additional external “booster” transistors for high current, high brightness LEDs. Up to three external transistors BCX68 or BC817SU each could be used on the PCB to minimize thermal problems.

3 LEDs in series for high current mode or 3 LEDs for low current applications can be chosen by setting resistors (see Figure 4). The particular sense voltage can be derived by jumpers which are provided in the layout for each test case. Additional test circuit is included to measure AC characteristics, and the ENABLE input is designed to connect a PWM signal. The PCB is manufactured in double sided FR4 with substrate thickness of 1.0 mm.

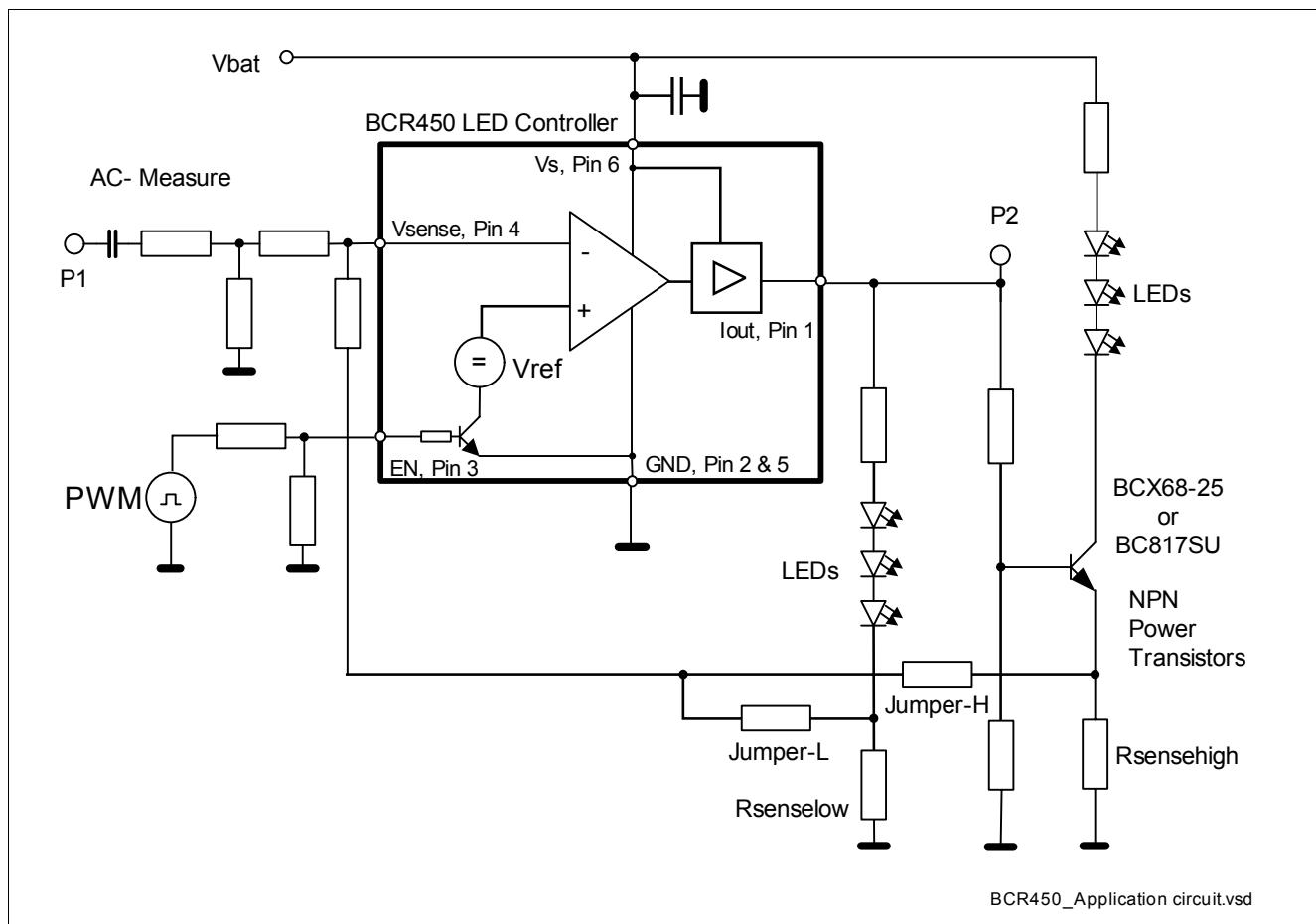
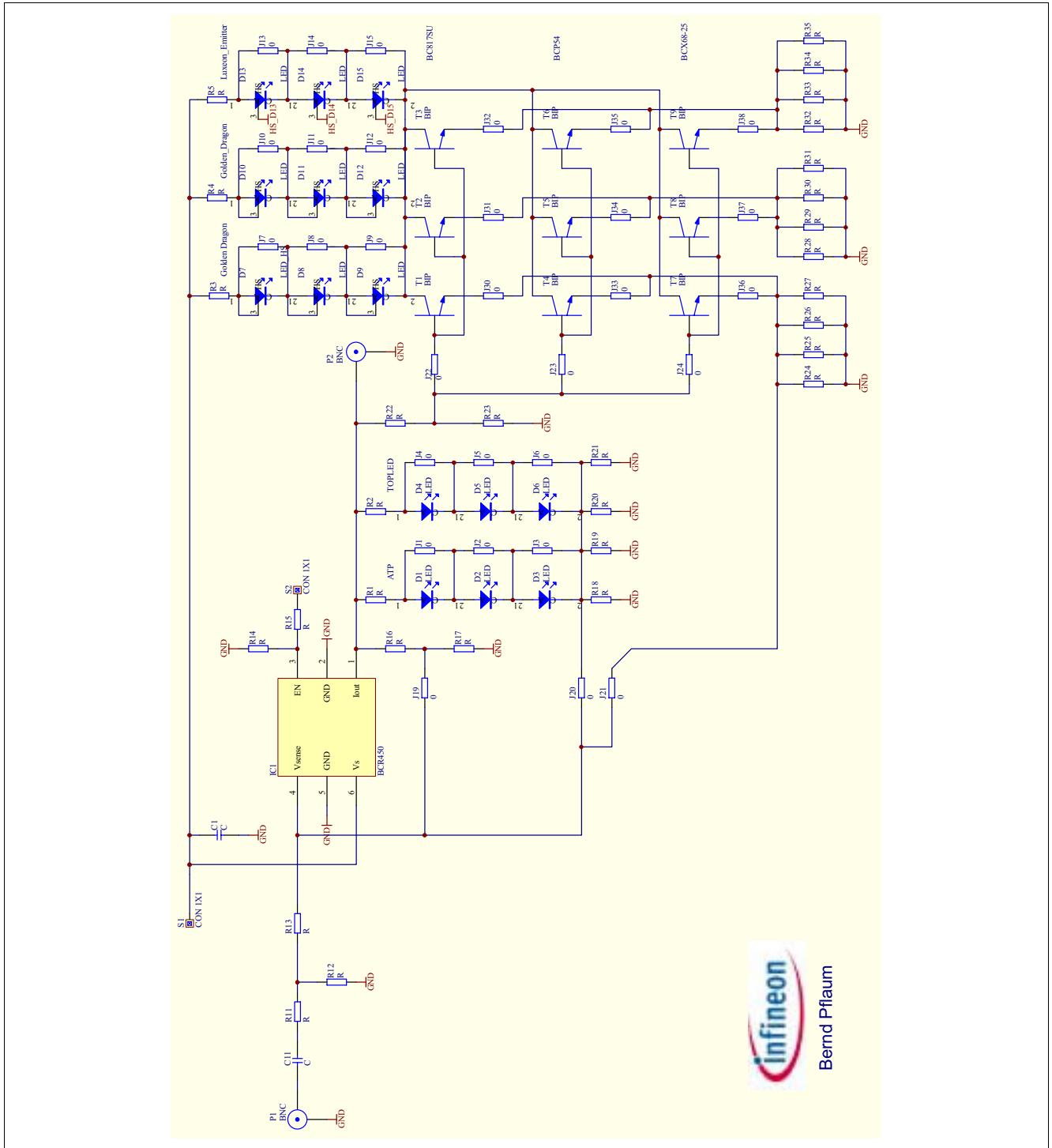


Figure 5 Evaluation board schematic


**Figure 6** Detailed evaluation board schematic

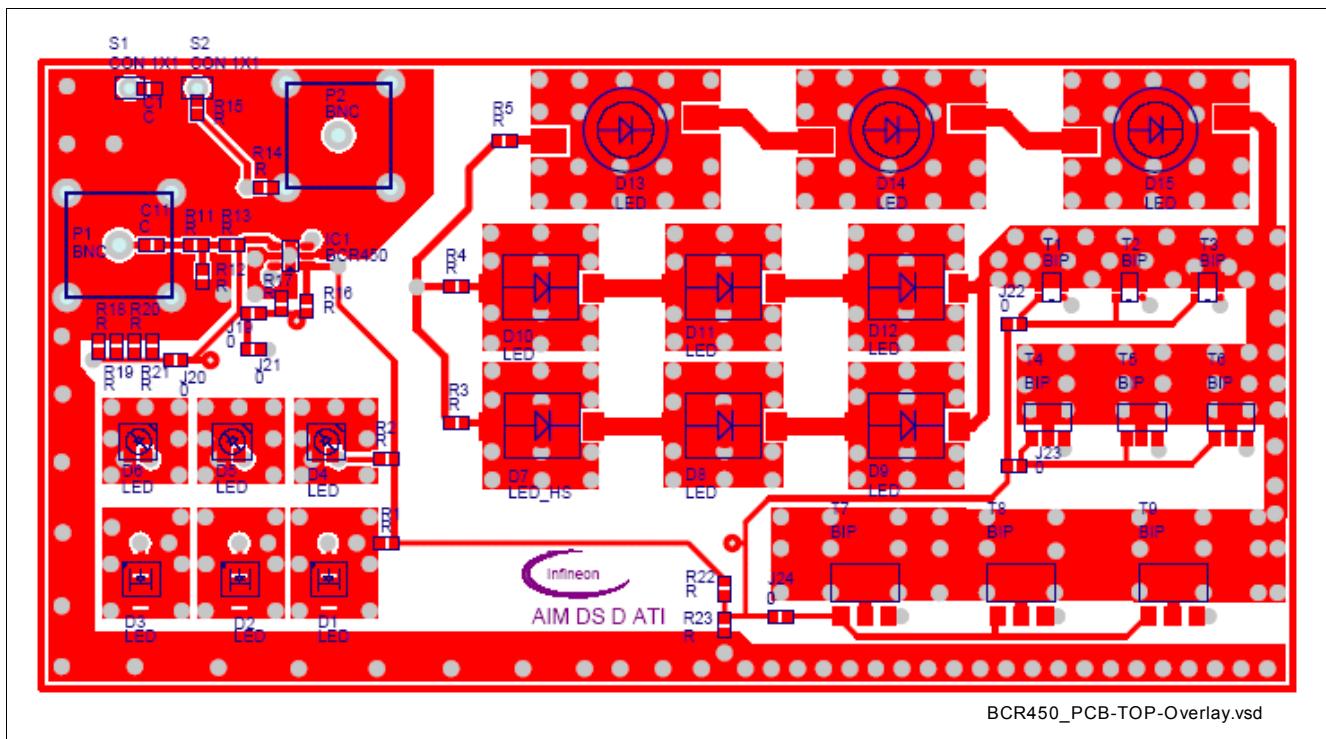


Figure 7 Top view on evaluation board (dimension 60 mm x 120 mm)

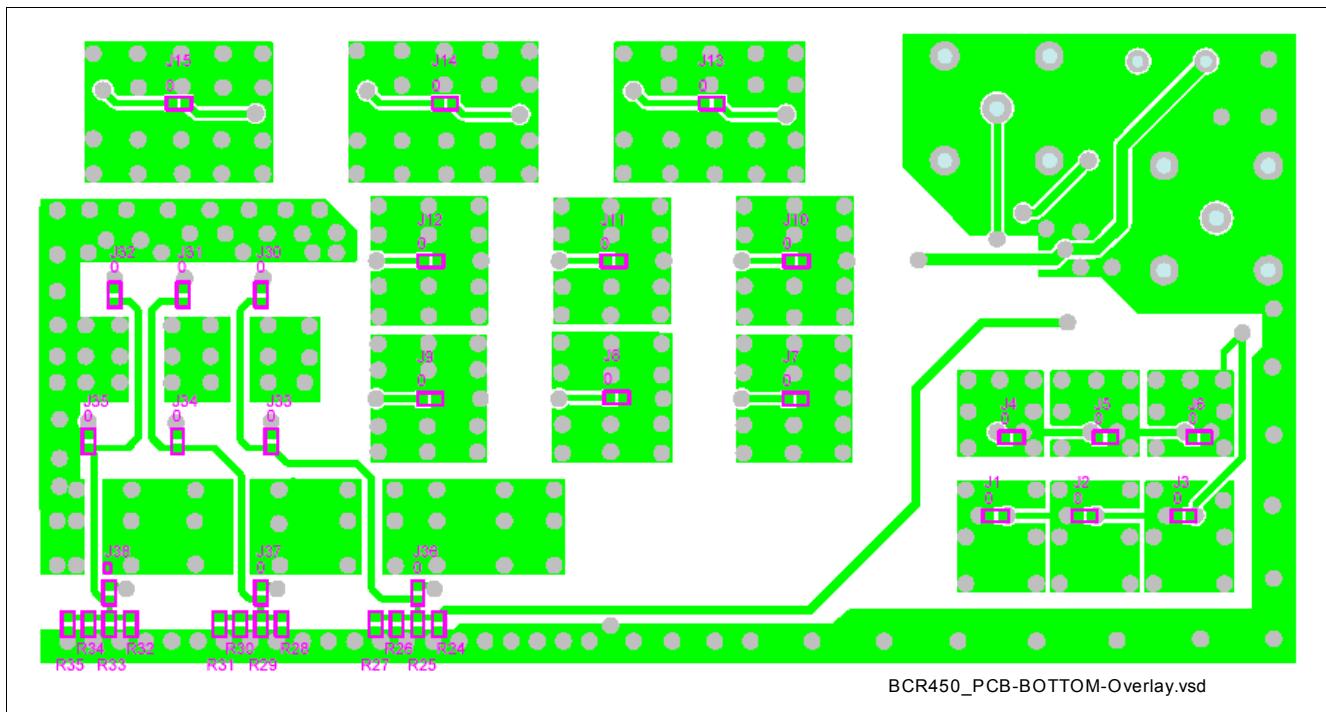
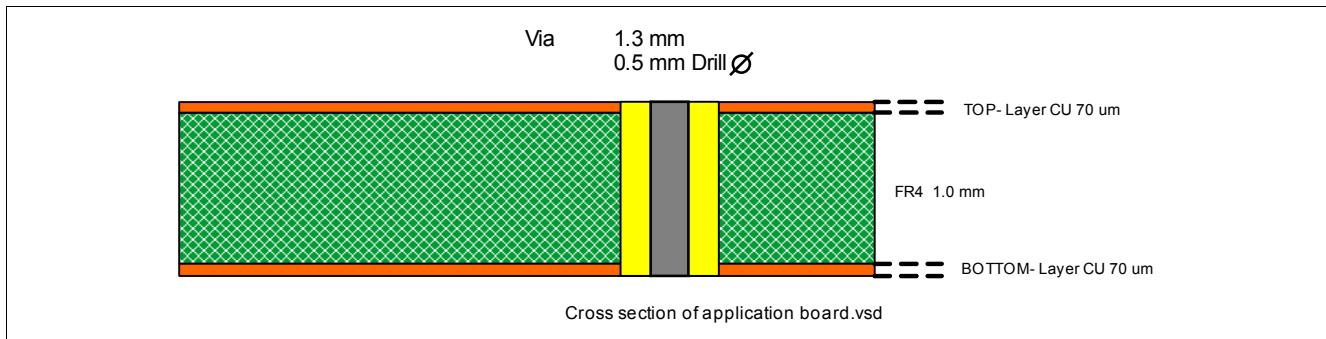
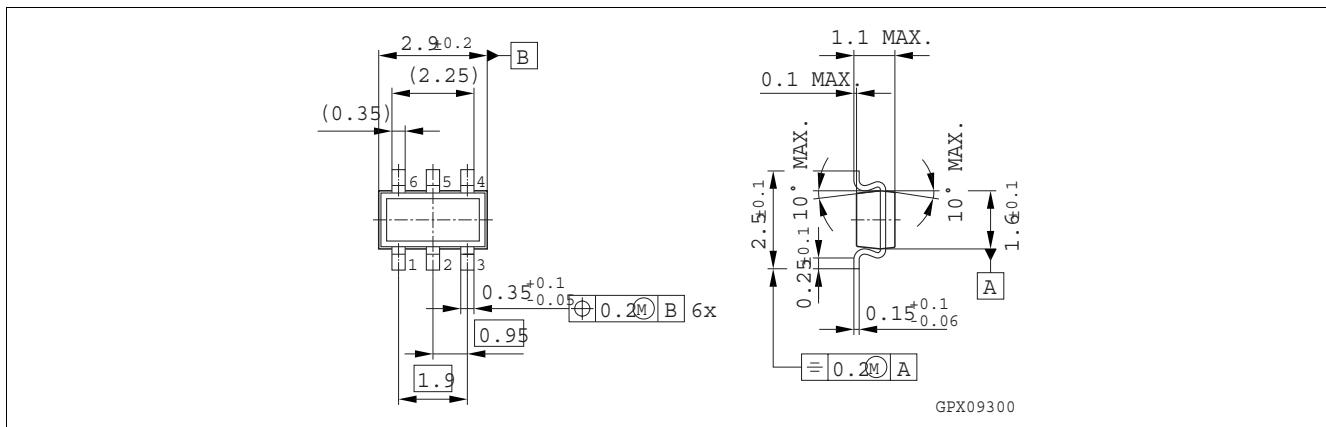


Figure 8 Bottom view on evaluation board (dimension 60 mm x 120 mm)

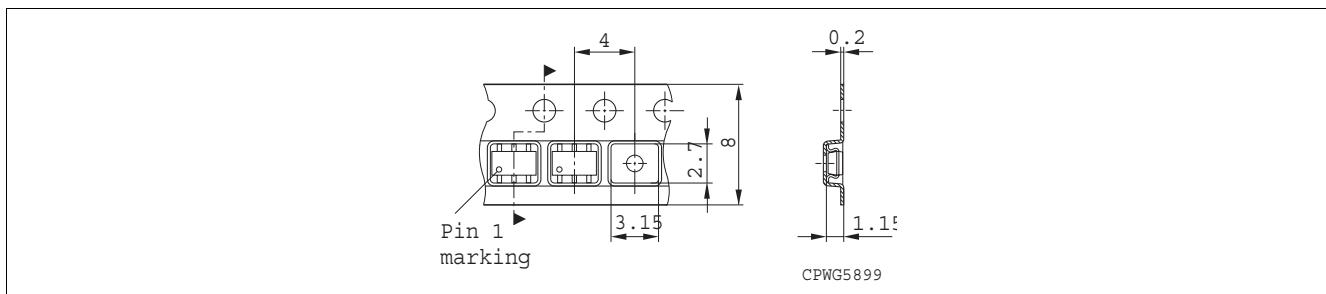


**Figure 9 Cross section of evaluation board**

## 6 Package Information



**Figure 10 Package outline; TSOP6 / SC74**



**Figure 11 Tape loading**